

TEKNIIKAN MATEMATIIKKA

Signaalianalyysi 031080A

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1. Määritellään diskreetti signaali $x(n) = \{-3, 0, -1, 6\}$. Laske signaalin $x(n)$

- (a) energia (1 p)
 - (b) keskimääräinen teho (1 p)
 - (c) autokorrelaatio $r_{xx}(n)$ (1 p)
 - (d) diskreetti Fourier muunnos $X(k)$ ja amplitudispektri. (3 p)
2. (a) Analogisesta signaalista $x(t) = \sin(30000\pi t)$ otetaan näytteitä $4 \cdot 10^{-5}$ sekunnin välein. Tapahtuuko laskostumista? Mikä analoginen taajuus vastaa saatua diskreettiä signaalia? Mikä on riittävä näytteenottotaajuus laskostumisen estämiseksi?
- (b) Analogisen LTI-systeemi on määritelty differentiaaliyhtälöllä

$$y'(t) + 7y(t) = 2x(t - 5), \quad y(0) = 0 \text{ ja } x(t) = 0, t < 0.$$

missä $x(t)$ on heräte ja $y(t)$ vaste. Määrää

- i. siirtofunktio,
 - ii. amplitudivaste,
 - iii. impulssivaste.
3. Olkoon $Y(t) = X(t) \cos(t + \Theta)$, missä $\Theta \sim \text{Tas}(0, 2\pi)$. $X(t)$ on Θ :sta riippumaton satunnaissignaali, jonka odotusarvofunktio on $E[X(t)] = 0$ ja autokorrelaatiofunktio on $R_X(\tau) = e^{-|\tau|}$. Laske $Y(t)$:n odotusarvofunktio, autokorrelaatiofunktio ja määrää $Y(t)$:n keskimääräinen teho. Tutki onko $Y(t)$ stationaarinen.
4. (a) Selitä mitä tarkoittaa valkoinen kohina. (1 p)
- (b) Laske tehtävän 2.(b) systeemin vasteen tehotiheyspektri ja autokorrelaatiofunktio, kun heräte on valkoista kohinaa, jonka tehotiheys on 1. (2 p)
- (c) Signaalia X_n estimoidaan aiempien näytteiden lineaarikombinaationa

$$X_n \approx Y_n = h_1 X_{n-1} + h_2 X_{n-2}$$

Määrää virheen $E[(X_n - Y_n)^2]$ minimoivat kertoimet h_1 ja h_2 , kun signaalin X_n autokorrelaatiofunktio $R_X(m)$ tunnetaan $R_X(0) = 6$, $R_X(1) = 3$, $R_X(2) = 2$. (3 p)

Table A. Properties of the Fourier transform
(TD = time domain, FD = frequency domain)

Property	Mathematical description
1. Linearity	$ag_1(t) + bg_2(t) \rightleftharpoons aG_1(f) + bG_2(f)$, where a and b are constants
2. Time scaling	$g(at) \rightleftharpoons \frac{1}{ a }G(\frac{f}{a})$, where a is a constant
3. Duality	If $g(t) \rightleftharpoons G(f)$, then $G(t) \rightleftharpoons g(-f)$
4. Time shifting	$g(t - t_0) \rightleftharpoons G(f)e^{-i2\pi ft_0}$
5. Frequency shifting	$g(t)e^{i2\pi f_0 t} \rightleftharpoons G(f - f_0)$
6. Area in TD	$\int_{-\infty}^{\infty} g(t) dt = G(0)$
7. Area in FD	$g(0) = \int_{-\infty}^{\infty} G(f) df$
8. Differentiation in TD	$\frac{d}{dt}g(t) \rightleftharpoons i2\pi fG(f)$
9. Integration in TD	$\int_{-\infty}^t g(\tau) d\tau \rightleftharpoons \frac{1}{i2\pi f}G(f) + \frac{G(0)}{2}\delta(f)$
10. Conjugate functions	If $g(t) \rightleftharpoons G(f)$, then $\overline{g(t)} \rightleftharpoons \overline{G(-f)}$
11. Multiplication in TD	$g_1(t)g_2(t) \rightleftharpoons G_1(f) * G_2(f)$
12. Convolution in TD	$g_1(t) * g_2(t) \rightleftharpoons G_1(f)G_2(f)$

Table C. Properties of the Fourier transform for discrete time signals

Property	Time domain	Frequency domain
Notation	$x(n)$	$X(\omega)$
	$y(n)$	$Y(\omega)$
1. Linearity	$ax(n) + by(n)$	$aX(\omega) + bY(\omega)$
2. Time shifting	$x(n - k)$	$e^{-i\omega k}X(\omega)$
3. Time reversal	$x(-n)$	$X(-\omega)$
4. Differentiation in FD	$nx(n)$	$i\frac{dX(\omega)}{d\omega}$
5. Convolution	$x(n) * y(n)$	$X(\omega)Y(\omega)$
6. Correlation	$r_{xy}(l) = x(-l) * y(l)$	$R_{xy}(\omega) = X(-\omega)Y(\omega)$

Table B. Fourier transform pairs

Time function	Fourier transform
1. $\text{rect}(\frac{t}{T})$	$T\text{sinc}(fT)$
2. $\text{sinc}(2Wt)$	$\frac{1}{2W}\text{rect}(\frac{f}{2W})$
3. $e^{-at}u(t), a > 0$	$\frac{1}{a + i2\pi f}$
4. $e^{-a t }, a > 0$	$\frac{2a}{a^2 + (2\pi f)^2}$
5. $e^{-\pi t^2}$	$e^{-\pi f^2}$
6. $\text{tri}(\frac{t}{T})$	$T\text{sinc}^2(fT)$
7. $\text{sinc}^2(Wt)$	$\frac{1}{W}\text{tri}(\frac{f}{W})$
8. $\delta(t)$	1
9. 1	$\delta(f)$
10. $\delta(t - t_0)$	$e^{-i2\pi ft_0}$
11. $e^{i2\pi f_0 t}$	$\delta(f - f_0)$
12. $\cos(2\pi f_0 t)$	$\frac{1}{2}[\delta(f - f_0) + \delta(f + f_0)]$
13. $\sin(2\pi f_0 t)$	$\frac{1}{2i}[\delta(f - f_0) - \delta(f + f_0)]$
14. $\text{sgn}(t)$	$\frac{1}{i\pi f}$
15. $\frac{1}{\pi t}$	$-i\text{sgn}(f)$
16. $u(t)$	$\frac{1}{2}\delta(f) + \frac{1}{i2\pi f}$
17. $\sum_{k=-\infty}^{\infty} \delta(t - kT_0)$	$\frac{1}{T_0} \sum_{n=-\infty}^{\infty} \delta(f - \frac{n}{T_0})$

Table D. Trigonometric identities

1. $e^{\pm i\theta} = \cos \theta \pm i \sin \theta$	6. $\sin(\alpha \pm \beta) = \sin \alpha \cos \beta \pm \cos \alpha \sin \beta$
2. $\cos \theta = \frac{1}{2}(e^{i\theta} + e^{-i\theta})$	7. $\cos(\alpha \pm \beta) = \cos \alpha \cos \beta \mp \sin \alpha \sin \beta$
3. $\sin \theta = \frac{1}{2i}(e^{i\theta} - e^{-i\theta})$	8. $\sin \alpha \sin \beta = \frac{1}{2}[\cos(\alpha - \beta) - \cos(\alpha + \beta)]$
4. $\sin^2 \theta + \cos^2 \theta = 1$	9. $\cos \alpha \cos \beta = \frac{1}{2}[\cos(\alpha - \beta) + \cos(\alpha + \beta)]$
5. $\cos^2 \theta - \sin^2 \theta = \cos(2\theta)$	10. $\sin \alpha \cos \beta = \frac{1}{2}[\sin(\alpha - \beta) + \sin(\alpha + \beta)]$

Property	Time domain	z-domain (=ZD)	Region of convergence
Notation	$x(n)$ $y(n)$	$X(z)$ $Y(z)$	$ROC_x = \{z \mid r_2 < z < r_1\}$ ROC_y
1. Linearity	$ax(n) + by(n)$	$aX(z) + bY(z)$	At least the intersection $ROC_x \cap ROC_y$
2. Time shifting	$x(n-k)$	$z^{-k}X(z)$	That of $X(z)$, except $z=0$, if $k > 0$ and $z=\infty$, if $k < 0$
3. Scaling in ZD	$a^n x(n)$	$X(a^{-1}z)$	$ a r_2 < z < a r_1$
4. Time reversal	$x(-n)$	$X(z^{-1})$	$\frac{1}{r_1} < z < \frac{1}{r_2}$
5. Differentiation in ZD	$nx(n)$	$-z \frac{dX(z)}{dz}$	$r_2 < z < r_1$
6. Convolution	$x(n) * y(n)$	$X(z)Y(z)$	At least $ROC_x \cap ROC_y$
7. Correlation	$r_{xy}(l) = x(-l) * y(l)$	$R_{xy}(z) = X(z^{-1})Y(z)$	At least $ROC\{X(z^{-1})\} \cap ROC_y$

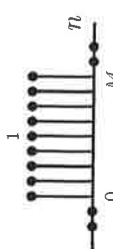
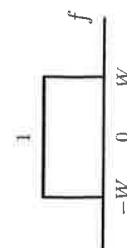
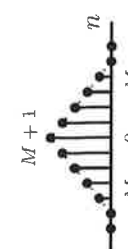
Table G. Functions

1. Rectangular function	$rect(t) = \begin{cases} 1, & -\frac{1}{2} < t < \frac{1}{2} \\ 0, & t > \frac{1}{2} \end{cases}$
2. Triangular function	$tri(t) = \begin{cases} 1- t , & t < 1 \\ 0, & t > 1 \end{cases}$
3. Unit step function (cont.)	$u(t) = \begin{cases} 1, & t > 0 \\ 0, & t < 0 \end{cases}$
4. Unit step function (discr.)	$u(n) = \begin{cases} 1, & n \geq 0 \\ 0, & n < 0 \end{cases}$
5. Signum function	$sgn(t) = \begin{cases} 1, & t > 0 \\ -1, & t < 0 \end{cases}$
6. Dirac delta function or equivalently	$\delta(t) = 0, t \neq 0, \int_{-\infty}^{\infty} \delta(t) dt = 1$ $\int_{-\infty}^{\infty} g(t) \delta(t-t_0) dt = g(t_0)$
7. Discrete delta function	$\delta(n) = \begin{cases} 1, & n = 0 \\ 0, & n \neq 0 \end{cases}$
8. Sinc function	$sinc(t) = \frac{\sin(\pi t)}{\pi t}$

Table H. Definitions

1.	$E_x = \int_{-\infty}^{\infty} x(t) ^2 dt$
2.	$P_x = \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T x(t) ^2 dt$
3.	$E_x = \sum_{n=-\infty}^{\infty} x(n) ^2$
4.	$P_x = \lim_{M \rightarrow \infty} \frac{1}{2M+1} \sum_{n=-M}^M x(n) ^2$
5.	$r_{xy}(mn) = \sum_{n=-\infty}^{\infty} x(n)y(n+mn)$
6.	$x(n) * y(n) = \sum_{k=-\infty}^{\infty} x(k)y(n-k)$
7.	$x(t) * y(t) = \int_{-\infty}^{\infty} x(\tau)y(t-\tau) d\tau$
8.	$X(f) = \int_{-\infty}^{\infty} x(t)e^{-i2\pi ft} dt$
9.	$x(t) = \int_{-\infty}^{\infty} X(f)e^{i2\pi ft} df$
10.	$X(k) = \sum_{n=0}^{N-1} x(n)e^{-i2\pi kn/N}$
11.	$x(n) = \frac{1}{N} \sum_{k=0}^{N-1} X(k)e^{i2\pi kn/N}$
12.	$X(\omega) = \sum_{n=-\infty}^{\infty} x(n)e^{-i\omega n}$
13.	$x(n) = \frac{1}{2\pi} \int_{-\pi}^{\pi} X(\omega)e^{i\omega n} d\omega$
14.	$X(z) = \sum_{n=-\infty}^{\infty} x(n)z^{-n}$
15.	$x(n) = \frac{1}{2\pi i} \int_{S_r} X(z)z^{n-1} dz$
16.	$Ae^{i\omega_0 n} \rightarrow AH(\omega_0)e^{i\omega_0 n}$

Table I. Fourier transform pairs

$g(n)$	$G(f)$, $-\frac{1}{2} < f < \frac{1}{2}$
1. 	$\frac{\sin(\pi f(M+1))}{\sin(\pi f)} e^{-i\pi f M}$
2. $\frac{\sin(2\pi W n)}{\pi n}$, $ W < \frac{1}{2}$	
3. 	$\left(\frac{\sin(\pi f(M+1))}{\sin(\pi f)} \right)^2$
4. $a^n u(n)$, $ a < 1$	$\frac{1}{1 - ae^{-i2\pi f}}$
5. $a^{ n }$, $ a < 1$	$\frac{1 - a^2}{1 - 2a \cos(2\pi f) + a^2}$
6. $\delta(n)$	1
7. 1	$\delta(f)$
8. $\delta(n-M)$	$e^{-i2\pi f M}$
9. $e^{-i2\pi f_0 n}$, $ f_0 < \frac{1}{2}$	$\delta(f - f_0)$
10. $\cos(2\pi f_0 n)$, $ f_0 < \frac{1}{2}$	$\frac{1}{2} \delta(f - f_0) + \frac{1}{2} \delta(f + f_0)$
11. $\sin(2\pi f_0 n)$, $ f_0 < \frac{1}{2}$	$\frac{1}{2i} (\delta(f - f_0) - \delta(f + f_0))$
12. $u(n)$	$\frac{1}{1 - e^{-i2\pi f}}$

Signal $x(n)$	z-transform $X(z)$	ROC
1. $\delta(n)$	1	All z
2. $u(n)$	$\frac{1}{1 - z^{-1}}$	$ z > 1$
3. $nu(n)$	$\frac{z^{-1}}{(1 - z^{-1})^2}$	$ z > 1$
4. $a^n u(n)$	$\frac{1}{1 - az^{-1}}$	$ z > a $

1. $X \sim \text{Poi}(\lambda)$, $\mu = \lambda$, $\sigma^2 = \lambda$, $P(X = k) = \frac{\lambda^k}{k!} e^{-\lambda}$, $k = 0, 1, 2, \dots$
2. $X \sim \text{Exp}(a)$, $\mu = \frac{1}{a}$, $\sigma^2 = \frac{1}{a^2}$, $f(x) = ae^{-ax}$, $x \geq 0$
3. $X \sim N(\mu, \sigma^2)$, $f(x) = \frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{1}{2}\left(\frac{x-\mu}{\sigma}\right)^2}$
4. $X \sim \text{Rayleigh}(\alpha)$, $\mu = \sqrt{\frac{\pi}{2\alpha}}$, $\sigma^2 = \frac{4-\pi}{2\alpha}$, $f(x) = \alpha x e^{-\frac{1}{2}\alpha x^2}$, $x \geq 0$
5. $Z_k = \alpha Z_{k-1} \pmod M$
6. $\{E[XY]\}^2 \leq E[X^2]E[Y^2]$
7. $C_Y = AC_X A^T$
8. $W(t) - W(s) \sim N(0, \sigma^2(t-s))$
9. $X(t) - X(s) \sim \text{Poi}[\lambda(t-s)]$
10. $X(t) = Y(t-A)$, $A \sim \text{Tas}(0, \Delta)$, $R_X(\tau) = 1 - |\tau|/\Delta$, $|\tau| \leq \Delta$
11. $X(t) = N(0, t)$, $P(N(0, t) = k) = \frac{(\lambda t)^k}{k!} e^{-\lambda t}$
12. $Z(t) = AY(t)$, $R_Z(\tau) = e^{-2\lambda|\tau|}$
13. $E[(\int_a^b X(t)dt)^2] = \int_a^b \int_a^b R_X(t_1, t_2) dt_1 dt_2$
14. $S_X(f) = \lim_{T \rightarrow \infty} \frac{E[|X_T(f)|^2]}{2T}$, $(R_X(t, t + \tau)) = \int_{-\infty}^{\infty} S_X(f) e^{i2\pi f \tau} df$
15. $S_X(f) = \int_{-\infty}^{\infty} R_X(\tau) e^{-i2\pi f \tau} d\tau$, $R_X(\tau) = \int_{-\infty}^{\infty} S_X(f) e^{i2\pi f \tau} df$
16. $S_X(f) = \sum_{k=-\infty}^{\infty} R_X(k) e^{-i2\pi f k}$, $R_X(k) = \int_{-1/2}^{1/2} S_X(f) e^{i2\pi f k} df$
17. $P_X = \int_{-\infty}^{\infty} S_X(f) df$
18. $Y(t) = h(t) * X(t) = \int_{-\infty}^{\infty} h(s) X(t-s) ds = \int_{-\infty}^{\infty} h(t-s) X(s) ds$
19. $Y_n = h_n * X_n = \sum_{j=-\infty}^{\infty} h_j X_{n-j}$
20. $H(f) = \int_{-\infty}^{\infty} h(t) e^{-i2\pi f t} dt$

21. $H(f) = \sum_{n=-\infty}^{\infty} h_n e^{-i2\pi f n}$
22. $S_Y(f) = |H(f)|^2 S_X(f)$
23. $R_{XY}(\tau) = R_X(\tau) * h(\tau)$
24. $S_{XY}(f) = H(f) S_X(f)$
25. $S_{YX}(f) = \overline{S_{XY}(f)} = \overline{H(f)} S_X(f)$
26. $H_{\text{opt}}(f) = \frac{1}{C} \frac{\overline{X(f)}}{S_N(f)} e^{-i2\pi f t_0}$
27. $H_{\text{opt}}(f) = \frac{S_{XZ}(f)}{S_X(f)}$, $X(t) = Z(t) + N(t)$
28. $H_{\text{opt}}(f) = \frac{S_Z(f)}{S_Z(f) + S_N(f)}$, $\epsilon = \int_{-\infty}^{\infty} \frac{S_Z(f) S_N(f)}{S_Z(f) + S_N(f)} df$
29. $Y_n = \sum_{k=a}^b h_k X_{n-k}$, $Y(t) = \int_a^b h(s) X(t-s) ds$
30. $X_k = Z_k + N_k$, $X(t) = Z(t) + N(t)$
31. $R_{XZ}(m) = \sum_{k=a}^b h_k R_X(m-k)$, $\epsilon = R_Z(0) - \sum_{k=a}^b h_k R_{XZ}(k)$
32. $R_{XZ}(\tau) = \int_a^b h(s) R_X(\tau-s) ds$, $\epsilon = R_Z(0) - \int_a^b h(s) R_{XZ}(s) ds$
33. $R_{XZ}(m) = \sum_{k=0}^{\infty} h_k R_X(m-k)$
34. $R_{XZ}(\tau) = \int_0^{\infty} h(s) R_X(\tau-s) ds$
35. $W(f) = 1/G(f)$, $S_X(f) = G(f) \overline{G(f)}$
36. $H_2(f) = \sum_{m=0}^{\infty} R_{X'Z}(m) e^{-i2\pi f m}$
37. $R_{X'Z}(k) = \sum_{i=0}^{\infty} w_i R_{XZ}(k+i)$, $S_{X'Z}(f) = S_{XZ}(f) \overline{G(f)}$
38. $H(f) = W(f) H_2(f)$